# A Re-Evaluation of the Over-Searching Phenomenon in Inductive Rule Learning



TECHNISCHE UNIVERSITÄT DARMSTADT

Frederik Janssen Johannes Fürnkranz



# Outline



- 1. Motivation
- 2. Separate-and-conquer Rule Learning
- 3. Search Strategies
  - Hill Climbing and Beam search
  - Exhaustive search
- 4. Rule Learning Heuristics
- 5. Results
  - Experimental Setup
  - Varying the beam size
  - Individual Datasets
  - Searching for single rules
- 6. Discussion

# 1. Motivation



- the phenomenon of over-searching, i.e., that more search has not to lead to better predicitve accuracy, was first shown by Quinlan and Cameron-Jones (1995)
- but they only used one heuristic and no true Exhaustive Search
- ▶ we extend their work to 9 different heuristics and a true Exhaustive Search
- no experimental results about the connection between the search heuristic and the search strategy
- we want to answer the question whether Separate-and-conquer (SECO) algorithms can improve from Exhaustive Search or bigger beams both in terms of theory size and accuracy or not

# 2. Separate-and-Conquer Rule Learning



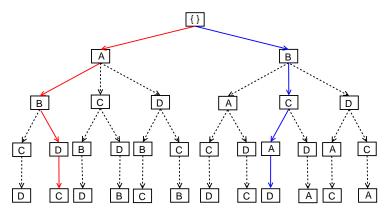
In the experiments we used a simple  $\operatorname{SECO}$  Rule Learner with the following properties:

- allows the usage of different heuristics and search strategies (Top-Down Beam Search)
- employs ordered class binarization
- classification is done by a decision list of rules
- does not perform pruning
- but implements Forward Pruning (important for the runtime)
  - create a virtual rule that covers the same number of positive examples but no negative instances
  - $\blacktriangleright$  if the evaluation of this rule is lower than that of the best rule  $\rightarrow$  stop refining this rule

3. Search Strategies

#### Hill-Climbing and Beam search



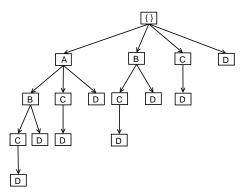


It is possible that a naive Beam search for  $b\to\infty$  generates more rules than the Exhaustive Search

#### 3. Search Strategies

#### Exhaustive search





Note that the implemented procedure follows  $OPUS^{\circ}$  (Webb, 1995), i.e., does not generate duplicates

# 4. Rule Learning Heuristics



heuristic		formula
Simple heuristics	Precision	$\frac{-p}{p+n}$
	Laplace	$\frac{p+1}{p+n+2}$
	Accuracy	p-n
	Weighted Relative Accuracy	$\frac{P}{P} - \frac{n}{N}$
	Odds ratio	$\frac{p \cdot (N-n)}{(P-p) \cdot n}$
	Correlation	$\frac{p \cdot (N-n) - n \cdot (P-p)}{\sqrt{P \cdot N \cdot (p+n) \cdot (P-p+N-n)}}$
Complex heuristics	Relative Cost Measure	$c \cdot rac{p}{P} - (1-c) \cdot rac{n}{N}$
	m-estimate	$\frac{p+m \cdot P/(P+N)}{p+n+m}$
	Meta-learned	learned f(p,n,P,N)

as suggested in (Janssen and Fürnkranz, 2008) the parameters were set to c = 0.342 and m = 22.466

#### **Experimental Setup**

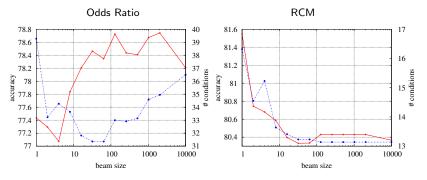


- 22 datasets from UCI Repository
- only nominal attributes in data (Exhaustive Search cannot handle numeric attributes at the moment)
- only small to medium size datasets (runtime of ES grows strongly with #attributes, #classes, #instances)
- Performance measure: macro average accuracy on many datasets estimated with 10-fold stratified CV
- expectation: runtime increases with increased beam sizes and positive effect of Exhaustive Search are
  - best visible when datasets are hard to learn
  - or when the Hill-climbing Search gets stuck in a local optimum

#### Varying the beam size



#### Example for consistent improvement/degradation

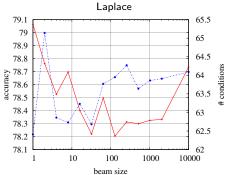


legend: blue dotted line = # conditions, red solid line = macro-average accuracy of CV, beam size 10000 = Exhaustive Search Algorithm, # conditions = conds. of all rules summed up

Varying the beam size



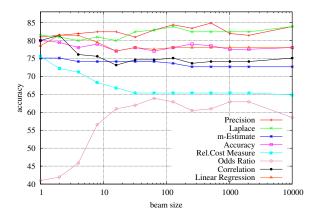
Example for strong fluctuations



Note that the final minor jump is due to different implementations of the Hill-climbing Search and the Exhaustive Search

#### Plot for individual dataset (autos-d)

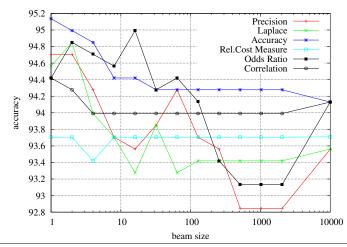




legend: macro-averaged accuracy of CV

#### Plot for individual dataset (breast-w-d)





Searching for single rules



interestingly the performance with one rule per class plus a default class is very good (about 10% less than the complete models)

examples:

- Precision: Hill-climbing Search 64.67% with 6.82 conditions, Exhaustive Search 68.55% with 9.59 conditions
- ▶ WRA: Hill-climbing Search 68.14% with 3.23 conditions, Exhaustive Search 68.81% with 3.5 conditions
- Precision and Laplace have significantly smaller theories (about 7 times smaller) than the full size model
- all heuristics gain performance from Exhaustive Search except for the Meta-learned one

# 6. Discussion



- the over-searching phenomenon depends on the heuristic
  - Odds Ratio and Precision gain performance
  - more complex heuristics lose performance
- heuristics that work well in Hill-climbing Search usually do not profit from Exhaustive Search or Beam search with bigger beam sizes
- experiments show that there are different requirements for heuristics used in Hill-climbing Search and Exhaustive Search
- mandatory next step:
  - separate the search heuristic (potential of a rule of beeing refined into a high quality rule) und the rule evaluation function (isolated measurement of the predictive quality of a rule)

#### References



- Quinlan and Cameron-Jones (1995): J. Ross Quinlan and R. Mike Cameron-Jones. Oversearching and layered search in empirical learning. In *IJCAI*, pages 1019-1024, 1995.
- (Webb, 1995): Geoffrey I. Webb. OPUS: An efficient admissible algorithm for unordered search. *Journal of Artificial Intelligence Research*, 3:431-465, 1995.
- (Janssen and Fürnkranz, 2008): Frederik Janssen and Johannes Fürnkranz. An empirical quest for optimal rule learning heuristics. Technical Report TUD-KE-2008-01, Technische Universität Darmstadt, Knowledge Engineering Group, 2008.
  http://www.ke.informatik.tu-darmstadt.de/publications/reports/tud-ke-2008-

http://www.ke.informatik.tu-darmstadt.de/publications/reports/tud-ke-2008-01.pdf.