
Lazy Rule Learning

Nikolaus Korfhage



TECHNISCHE
UNIVERSITÄT
DARMSTADT



Introduction

Lazy Rule Learning Algorithm

Possible Improvements

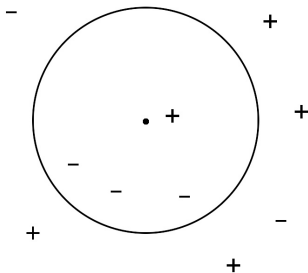
Improved Lazy Rule Learning Algorithm

Implementation

Evaluation and Results

- ▶ Learns classifier once on the training data to classify test instances
- ▶ Classifier → Rule set
- ▶ Separate-and-conquer
 - ▶ add rules that cover many positive examples

- ▶ Training data utilized by each query instance individually
- ▶ Classify instances simultaneously
- ▶ More time for classification



$$W_i = \frac{1}{d(\text{TestInstance}, x_i)}$$

- ▶ Combine lazy learning and rule learning
 - ▶ produces many context-less rules
- ▶ Learn **one** rule
- ▶ Rule consists of conditions from test instance
- ▶ Rule should classify test instance correctly
- ▶ Example:
 - ▶ Test instance: <rainy, 68, 80, FALSE>
 - ▶ Rule: play = yes :- windy = FALSE.
- ▶ # rules = # instances to classify



LAZYRULE (*Instance*, *Examples*)

InitialRule = \emptyset

BestRule = *InitialRule*

for *Class* \in *Classes*

Conditions \leftarrow POSSIBLECONDITIONS(*Instance*)

NewRule = REFINERULE (*Instance*, *Conditions*, *InitialRule*, *Class*)

if *NewRule* $>$ *BestRule*

BestRule = *NewRule*

return *BestRule*



POSSIBLECONDITIONS (*Instance*)

Conditions $\leftarrow \emptyset$

for *Attribute* \in *Attributes*

Value = ATTRIBUTEVALUE (*Attribute*, *Instance*)

if *Value* $\neq \emptyset$

Conditions = *Conditions* $\cup \{(Attribute = Value)\}$

return *Conditions*



REFINERULE (*Instance, Conditions, Rule, Class*)

if *Conditions* $\neq \emptyset$

BestRule = *Rule*

BestCondition = BESTCONDITION (*Rule, Conditions*)

Refinement = *Rule* \cup *BestCondition*

Evaluation = EVALUATERULE (*Refinement*)

NewRule = \langle *Evaluation, Refinement* \rangle

if *NewRule* $>$ *BestRule*

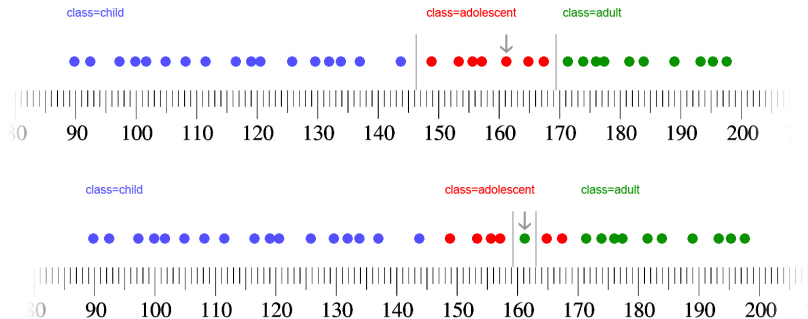
BestRule = *NewRule*

 REFINERULE (*Instance, Conditions* \setminus *BestCondition, NewRule, Class*)

return *BestRule*

- ▶ Test instance:
 <sunny, 85 ,85, FALSE>
- ▶ Condition *outlook = sunny*
 → covers some training examples
- ▶ but condition *temperature = 85*
 → covers **no** training example
- ▶ Solution
 → infer two conditions, e.g. $temperature \geq 80 \wedge temperature < 90$

Numeric Attributes



Example of Learned Rules



play = yes :- humidity < 88, humidity >= 70, windy = FALSE.

play = yes :- temperature >= 72, temperature < 84.

play = yes :- outlook = overcast.

play = yes :- humidity >= 70, humidity < 82.5, windy = FALSE.

play = no :- outlook = sunny, temperature >= 70.5, temperature < 80.5.

- ▶ LAZYPURE evaluated with heuristics available in SECO
- ▶ Laplace significantly better on most datasets
- ▶ Results:
 - ▶ Laplace 76.17
 - ▶ Linear Regression 72.44
 - ▶ *F*-Measure 70.62
 - ▶ Linear Cost 69.17
 - ▶ *m*-Estimate 68.81
 - ▶ Foil Gain 65.99
 - ▶ ...

- ▶ # rules to check for one test instance: $O(c \cdot a^2)$
- ▶ # rules all instances: $O(c \cdot a^2 \cdot d)$
- ▶ # instances to check on first call REFINERULE: $c \cdot a \cdot t$
- ▶ Decrease a or t

c : # classes

a : # attributes

d : # instances to classify

t : # training instances

- ▶ Increase accuracy
 - ▶ Beam search

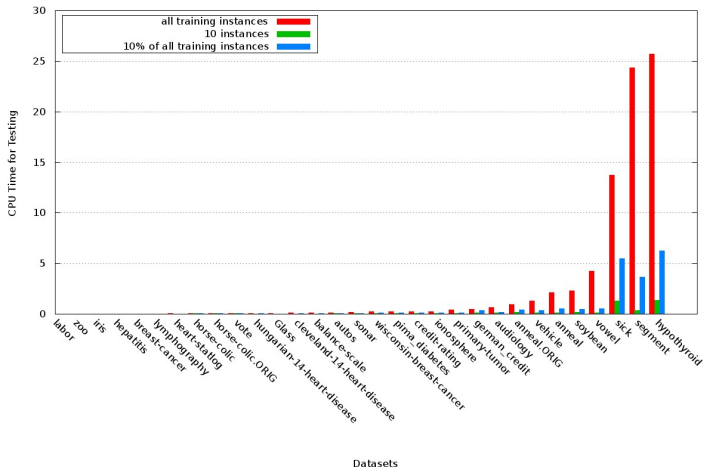
- ▶ Reduce execution time
 - ▶ Consider less data → random subset of training data
 - ▶ Preselect attributes

- ▶ Increase accuracy and decrease execution time
 - ▶ Learn rules on k -nearest neighbors



- ▶ Learn rule on k -nearest neighbors
- ▶ Less training data to learn rule on
→ faster
- ▶ Consider only useful instances to learn rule on
→ higher accuracy

Computation Time



Accuracy

Dataset	LAZYRULE	LAZYRULENN, $k = 5$
iris	94.27	95.40
labor	85.67	88.20
balance-scale	85.44	86.16
heart-statlog	70.63	79.33 ○
zoo	77.10	96.35 ○
hepatitis	79.70	84.91
Glass	61.10	66.77
wisconsin-breast-cancer	91.47	96.81 ○
lymphography	76.16	84.11
breast-cancer	72.15	73.37
autos	65.45	68.81
hungarian-14-heart-disease	80.41	82.52
primary-tumor	41.18	43.45
credit-rating	84.55	86.17
cleveland-14-heart-disease	75.59	83.08 ○
pima-diabetes	69.91	73.84
vote	94.05	93.38
horse-colic.ORIG	71.92	63.02 ●
audiology	48.30	66.02 ○
vehicle	52.74	70.56 ○
horse-colic	81.79	82.15
ionosphere	91.91	85.36 ●
anneal.ORIG	89.21	94.42 ○
vowel	29.42	93.67 ○
sonar	64.14	82.42 ○
anneal	90.75	98.24 ○
german-credit	70.84	73.11
soybean	80.08	91.07 ○
sick	93.88	96.28 ○
segment	73.89	95.68 ○
hypothyroid	92.86	93.43
Average	75.37	82.84

significance level: 0.01

improvement

degradation

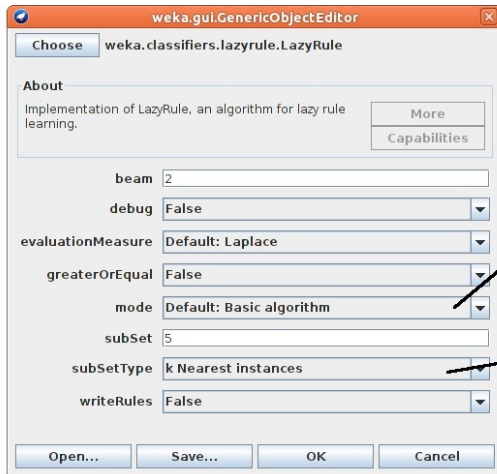
- ▶ Shorter rules for small k
- ▶ More empty rules

	LAZYRULE	LAZYRULENN $>, k = 5$	LAZYRULENN $\geq, k = 5$
Accuracy (%)	75.41	82.86	82.86
Average Rule Length	2.88	0.89	19.56
Empty Rules (%)	0.01	54.41	1.78

- ▶ Based on SECo-framework
 - ▶ Rules
 - ▶ Heuristics

- ▶ Weka:
 - ▶ Evaluation
 - ▶ Interface
 - ▶ kNN

Weka Interface



- hillclimbing
- beam
- all

- k nearest neighbors
- % nearest neighbors
- k random instances
- % random instances

- ▶ 37 datasets
- ▶ Evaluating possible improvements:
 - ▶ Weka: ten-fold CV
 - ▶ Corrected paired Student's t-Test
 - ▶ Leave-one-out cross-validation
- ▶ Comparing algorithms:
 - ▶ Weka: ten-fold CV
 - ▶ Friedman test with post-hoc Nemenyi test



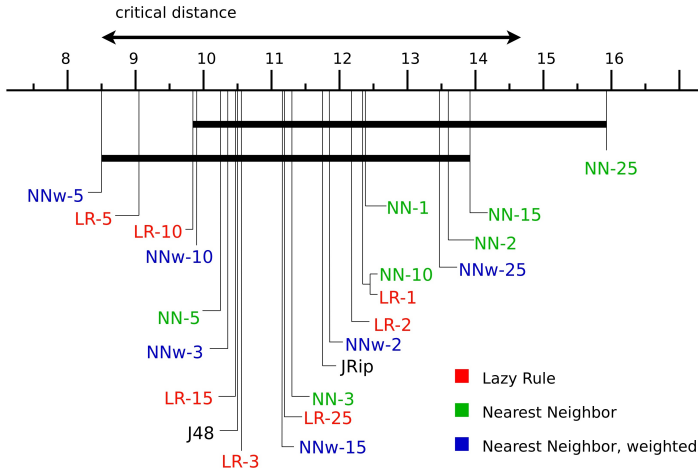
Compared to:

- ▶ Decision tree algorithm J48 (C4.5)
- ▶ Separate-and-conquer rule learning algorithm JRip (RIPPER)
- ▶ k -nearest neighbor
- ▶ Weighted k -nearest neighbor
- ▶ $k = 1, 2, 3, 5, 10, 15, 25$

► Average accuracy

	$k = 1$	$k = 2$	$k = 3$	$k = 5$	$k = 10$	$k = 15$	$k = 25$
LAZYRULENN	83.31	83.02	84.00	83.90	82.94	82.47	82.09
kNN	83.35	82.75	83.73	83.47	81.73	80.23	78.18
kNN, weighted	83.35	83.29	84.16	84.27	83.69	83.29	82.14
JRip	83.09						
J48	83.37						

Results



- ▶ Combines lazy learning and rule learning
- ▶ Improved lazy rule learning algorithm uses kNN
- ▶ Not significantly worse than considered learning algorithms
- ▶ Learns many context-free rules (one for each instance)
- ▶ May be useful for other projects (e.g. Learn-a-LOD)