



Incremental Algorithms for Hierarchical Classification

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Overview



- Introduction
- H-Loss
- H-RLS
- Analysis
- Experiments

Introduction

H-Loss

H-RLS

Analysis

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Introduction



- Hierarchical online classifier
- Data is produced frequently / in large amount
- Classification scenario:
 - Data
 - Hierarchy
 - Linear-threshold classifier for each node
 - Evaluation

Introduction



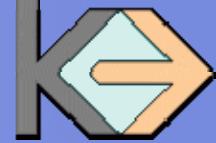
- Notation:

- Instance $x \in \mathbb{R}^N$
- Label / multilabel $v = (v_1, v_2, \dots, v_N) \in \{0, 1\}^N$
- Example (x, v)
- Taxonomy G (forest of trees)
- Multilabel respects taxonomy

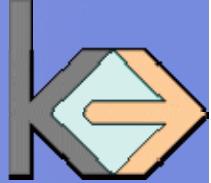
Introduction



- Notation:
 - $\text{Anc}(i)$
 - $\text{Par}(i)$
 - $\text{Root}(G)$
- Multi-/partial-path labelling



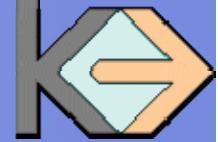
- H-RLS algorithm basics
- Loss functions:
 - Zero-one loss $l_{0/1}$
 - Symmetric difference loss l_Δ
 - H-Loss l_H



- H-Loss:

$$l_H(\hat{y}, v) = \sum_{t=1}^N \{\hat{y}_i \neq v_i \wedge \hat{y}_j = v_j, j \in ANC(t)\}$$

- $l_{0/1} \leq l_H \leq l_\Delta$



- H-RLS = Hierarchical – Regularized Least Squares
- Online algorithm
- N linear-threshold classifier
- Label all root nodes
- Label all children of nodes labelled with 1

Algorithm H-RLS.

Initialization: Weight vectors $w_{i,1} = (0, \dots, 0)$, $i = 1, \dots, N$.

For $t = 1, 2, \dots$ do

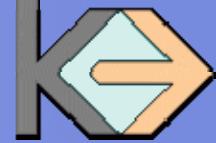
1. Observe instance $x_t \in \{x \in \mathbb{R}^d : \|x\| = 1\}$;
2. For each $i = 1, \dots, N$ compute predictions $\hat{y}_{i,t} \in \{0, 1\}$ as follows:

$$\hat{y}_{i,t} = \begin{cases} \{w_{i,t}^\top x_t \geq 0\} & \text{if } i \text{ is a root node,} \\ \{w_{i,t}^\top x_t \geq 0\} & \text{if } i \text{ is not a root node and } \hat{y}_{j,t} = 1 \text{ for } j = \text{PAR}(i), \\ 0 & \text{if } i \text{ is not a root node and } \hat{y}_{j,t} = 0 \text{ for } j = \text{PAR}(i), \end{cases}$$

where

$$\begin{aligned} w_{i,t} &= (I + S_{i,Q(i,t-1)} S_{i,Q(i,t-1)}^\top + x_t x_t^\top)^{-1} \times \\ &\quad \times S_{i,Q(i,t-1)} (v_{i,i_1}, v_{i,i_2}, \dots, v_{i,i_{Q(i,t-1)}})^\top \\ S_{i,Q(i,t-1)} &= [x_{i_1} \ x_{i_2} \ \dots \ x_{i_{Q(i,t-1)}}] \quad i = 1, \dots, N. \end{aligned}$$

3. Observe multilabel v_t and update weights.



- Standard perceptron weight update:

$$w_{ij}^{\text{neu}} = w_{ij}^{\text{alt}} + \Delta w_{ij}$$

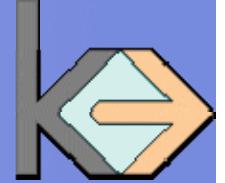
$$\Delta w_{ij} = \alpha(t_j - o_j) \cdot x_i$$

- Old weight is basis value for new weight

- H-RLS weight update:

$$w_{i,t} = \left(I + S_{i,Q(i,t-1)} S_{i,Q(i,t-1)}^\top + x_t x_t^\top \right)^{-1} S_{i,Q(i,t-1)} (v_{i,i_1}, \dots, v_{i,i_{Q(i,t-1)}})^\top$$

- Indirect influence of old weights



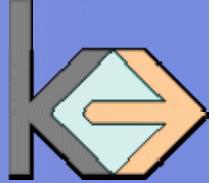
- Weight update: $w_{i,t} = \left(I + S_{i,Q(i,t-1)} S_{i,Q(i,t-1)}^\top + x_t x_t^\top \right)^{-1} S_{i,Q(i,t-1)} (v_{i,i_1}, \dots, v_{i,i_{Q(i,t-1)}})^\top$

- With: $Q(i,t) = |\{1 \leq s \leq t : v_{\text{PAR}(i),s} = 1\}|$

$$S_{i,Q(i,t-1)} = [x_{i_1} x_{i_2} \dots x_{i_{Q(i,t-1)}}]$$

$$(v_{i,i_1}, v_{i,i_2}, \dots, v_{i,i_{Q(i,t-1)}})$$

Analysis



- Evaluate performance of the algorithm
- Find error-bound
- Label generation

– Probability distribution

$$f_G(v \mid x) = \prod_{i=1}^N \mathbb{P}(V_i = v_i \mid V_j = v_j, j = \text{PAR}(i), x)$$

– Respect taxonomy

$$\mathbb{P}(V_i = 1 \mid V_j = 0, x) = 0$$

– Probability for node (non root)

$$\mathbb{P}(V_i = 1 \mid V_j = 1, x) = \frac{1 + u_i^\top x}{2}.$$

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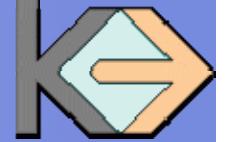
H-Loss

H-RLS

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Analysis



- Reference classifier
 - Built on true parameters u_i
 - Same form as H-RLS

$$y_i = \begin{cases} \{u_i^\top x \geq 0\} & \text{if } i \text{ is a root node,} \\ \{u_i^\top x \geq 0\} & \text{if } i \text{ is not a root and } y_j = 1 \text{ for } j = \text{PAR}(i), \\ 0 & \text{if } i \text{ is not a root and } y_j = 0 \text{ for } j = \text{PAR}(i). \end{cases}$$

- Create multilabel distribution, as shown before

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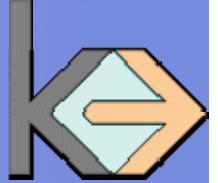
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- Cumulative regret $\sum_{t=1}^T (\mathbb{E} \ell(\hat{y}_t, V_t) - \mathbb{E} \ell(y_t, V_t))$
- Will hold theoretical regret bound

$$\sum_{t=1}^T (\mathbb{E} \ell_H(\hat{y}_t, V_t) - \mathbb{E} \ell_H(y_t, V_t)) \leq 16(1 + 1/\epsilon) \sum_{i=1}^N \frac{C_i}{\Delta_i^2} \mathbb{E} \left[\sum_{j=1}^d \log(1 + \lambda_{i,j}) \right],$$

where

$$\Delta_{i,t} = u_i^\top x_t, \quad \Delta_i^2 = \min_{t=1, \dots, T} \Delta_{i,t}^2, \quad C_i = |\text{SUB}(i)|,$$

- w_i is an asymptotically unbiased estimator for u_i

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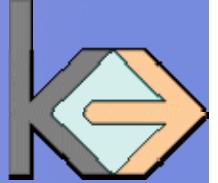
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- Theoretical regret bound

$$\sum_{t=1}^T (\mathbb{E} \ell_H(\hat{y}_t, V_t) - \mathbb{E} \ell_H(y_t, V_t)) \leq 16(1 + 1/e) \sum_{i=1}^N \frac{C_i}{\Delta_i^2} \mathbb{E} \left[\sum_{j=1}^d \log(1 + \lambda_{i,j}) \right],$$

where

$$\Delta_{i,t} = u_i^\top x_t, \quad \Delta_i^2 = \min_{t=1,\dots,T} \Delta_{i,t}^2, \quad C_i = |\text{SUB}(i)|,$$

- Depends on hierarchy structure
- The deeper the node i, the less the contribution
- Cost sensitive H-Loss

$$\ell_H(\hat{y}, v) = \sum_{i=1}^N c_i \{\hat{y}_i \neq v_i \wedge \hat{y}_j = v_j, j \in \text{ANC}(i)\},$$

Introduction

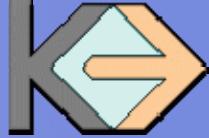
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Experiments



Newswire stories from Reuters Corpus Volume 1
(first 100.000 stories)

- Taxonomy: document topics, 101 nodes
- 5 experiments, adjacent pair = training & test set

Subtree of „Quality of Health Care“ (55.503 documents)

- Taxonomy: remove cycles, 94 nodes
- 5 experiments, 40.000 training & 15.503 test

Experiments



- Linear grow of space complexity => SH-RLS
- Algorithms
 - Hierarchical: H-PERC, H-SVM
 - Flat: PERC, SVM, S-RLS

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Experiments

RCV1			
Algorithm	zero-one loss	uniform H-loss	Δ -loss
PERC	0.702(± 0.045)	1.196(± 0.127)	1.695(± 0.182)
H-PERC	0.655(± 0.040)	1.224(± 0.114)	1.861(± 0.172)
S-RLS	0.559(± 0.005)	0.981(± 0.020)	1.413(± 0.033)
SH-RLS	0.456(± 0.010)	0.743(± 0.026)	1.086(± 0.036)
SVM	0.482(± 0.009)	0.790(± 0.023)	1.173(± 0.051)
H-SVM	0.440(± 0.008)	0.712(± 0.021)	1.050(± 0.027)

OHSUMED			
Algorithm	zero-one loss	uniform H-loss	Δ -loss
PERC	0.899(± 0.024)	1.938(± 0.219)	2.639(± 0.226)
H-PERC	0.846(± 0.024)	1.560(± 0.155)	2.528(± 0.251)
S-RLS	0.873(± 0.004)	1.814(± 0.024)	2.627(± 0.027)
SH-RLS	0.769(± 0.004)	1.200(± 0.007)	1.957(± 0.011)
SVM	0.784(± 0.003)	1.206(± 0.003)	1.872(± 0.005)
H-SVM	0.759(± 0.002)	1.170(± 0.005)	1.910(± 0.007)

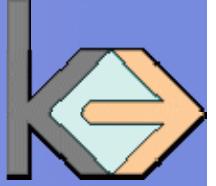
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Thank you for your attention

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