# **Monte-Carlo Methods**



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# **Outline**



- Minimax
- Expected Outcome
- Monte-Carlo
	- Monte-Carlo Simulation
	- Monte-Carlo Tree Search
	- **UCT**
	- AMAF
	- RAVE
	- **MC-RAVE**
	- UCT-RAVE
- Playing Games
	- Go, Bridge, Scrabble
- Problems with MC
	- **Laziness**
	- **Basin structure**
	- **Dangers of Random playouts**

# **Minimax**

- Assume that black is first to move
- Outcome of a game is either
	- $0 =$  win for white
	- $\blacksquare$  1 = win for black
- Black wants to maximize the outcome
- White wants to minimize it
- Given a small enough game tree (or enough time) minimax can be used to compute perfect play
- Problem: this is not always possible

$$
\texttt{ev}_c(p) = \left\{ \begin{aligned} &\texttt{ev}(p), && \textit{if $\texttt{ev}(p) \in [0,1]$;} \\ &\max_{p' \in s(p)} \texttt{ev}_c(p'), && \textit{if $\texttt{ev}(p) = \texttt{max}$;} \\ &\min_{p' \in s(p)} \texttt{ev}_c(p'), && \textit{if $\texttt{ev}(p) = \texttt{min}$.} \end{aligned} \right.
$$

ev:  $G \rightarrow \{ \max, \min \} \cup [0, 1]$ 

if  $ev(p) \in [0,1]$  return  $ev(p)$ if  $ev(p) = max$  return  $max_{p' \in s(p)}$  minimax $(p')$ if  $ev(p) = min$  return  $min_{p' \in s(p)}$  minimax $(p')$ 



$$
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$$



- Bruce Abramson (1990)
	- Used the idea of simulating random playouts of a game position
	- Concerns: Minimax approach has several problems
		- **Hard to calculate, hard to estimate**
		- Misses precision to extend beyond two-player games
	- He proposes a domain-independent model of static evaluation
		- Namely the Expected Outcome of a game given random play



Expected outcome is defined as

$$
EO(G) = \sum_{leaf=1}^{k} V_{leaf} P_{leaf}
$$

- where
	- $G =$  game tree node
	- $\bullet$   $k = \text{\#}$  leafs in subtree
	- $V_{leaf}$  leafs value
	- $P_{leaf}$  probability that leaf will be reached, given random play





$$
EO(G) = \left(1 * \frac{1}{2} + 0 * \frac{1}{4} + 1 * \frac{1}{2}\right) = \frac{3}{4}
$$

EO(G) is the chance of winning when playing the move that leads to G.



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- Problem
	- The perfect play assumption is easily defended
	- The random play assumption on the other hand not really
		- A strong move against a random player does not have to be good against a real one
- Consider this hypothetical scenario
	- Two identical chess midgame positions
	- Human player has 1 minute to make a move on each board
	- Board 1 is then played out randomly, whereas board 2 is played out by (oracularly defined) minimax play
	- Obviously on board 1 the player wants to play the move with the highest EO, whereas on board 2 he wants to play the strongest minimax move

#### **Assumption: The correct move is frequently (not always) the same**



- Apply EO methods to games with incomplete information (e.g. games where the game tree is too big)
- Example Othello (8x8)
	- $\blacksquare$  FO has to be estimated
	- Do this by sampling a finite number of random playouts
		- Sample N = 16 leaves, calculate  $\mu_0 = \frac{WINS}{N}$  $\boldsymbol{N}$

• Then  $\mu_1 = \frac{WINS}{2N}$  $\frac{\mu_{INS}}{2N}$ , ...  $\mu_i = \frac{WINS}{2^iN}$  $\frac{\mu_{IN3}}{2^{i}N}$  until  $|\mu_i - \mu_{i-1}| \leq \epsilon$ 

- This Sampler beat Weighted-Squares (fairly strong) 48-2
	- Although it occasionally took >2h to make a move
	- Disk Difference shows that Sampler is a full class better than Weighted-Squares

# **Monte-Carlo Simulation**



- Monte-Carlo Tree Search and Rapid Action value Estimation in Computer Go (Gelly and Silver, 2011)
- Definition:

$$
Q(s, a) = \frac{1}{N(s, a)} \sum_{i=1}^{N(s)} \mathbb{I}_i(s, a) z_i
$$

- Where
	- $N(s,a) = #$  of times action a was selected in state s,  $z_i$  = value of ith simulation,  $N(s)$  = the total number of simulations
	- $I_i(s, a)$  = A function that return 1 if action a was selected in state s and 0 otherwise



- Uses MC Simulation to evaluate the nodes of a search tree
- How to generate
- **Start with an empty Tree T**
- Every simulation adds one node to the T (the first node visited that is not yet in the tree)
- After each simulation every node in T updates it's MC value
- As the tree grows bigger the node values approximate the minimax value ( $n \rightarrow$  infinity)









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- Idea: optimism in case of uncertainty when searching the tree
	- Greedy action selection typically avoids searching actions after one or more poor outcomes
	- UCT treats each state of the search tree as a multi-armed bandit
		- The action value is augmented by an exploration bonus that is highest for rarely visited state-action pairs
		- The tree policy selects the action a\* maximizing the augmented value

$$
Q^{\oplus}(s, a) = Q(s, a) + c \sqrt{\frac{\log N(s)}{N(s, a)}}
$$
  
\n**c** = **Exploration**  
\n**c**onstant  
\n
$$
a^* = \operatorname{argmax}_{a} Q^{\oplus}(s, a)
$$

# **All Moves As First Heuristic**



- MC alone can't generalize between related positions
- **Idea: have one general value for each move independent from** when it's played
- Combine all branches where an action a is played at any point after s
- MC simulation can be used to approximate the AMAF value

$$
\tilde{Q}(s, a) = \frac{1}{\tilde{N}(s, a)} \sum_{i=1}^{N(s)} \tilde{\mathbb{I}}_i(s, a) z_i,
$$

Gelly and Silver (2011) used this in computer Go

# **Rapid Action Value Estimation**



- The RAVE algorithm uses the all-moves-as-first heuristic to share knowledge between nodes
	- As normal MC has to play out many games for any action in any state it is a good idea to save capacity by using the AMAF heuristic
		- Moves are often unaffected by moves played elsewhere on the board
		- $\bullet$   $\rightarrow$  One general value for each move
	- Especially in GO the branching factor is very big

# **MC-RAVE**



- The RAVE algorithm learns very quickly, but is often wrong
	- Idea: Combine the RAVE value with the MC value and make decisions based on that
	- Each node in the Tree then has an AMAF and a MC value

$$
Q_{\star}(s, a) = (1 - \beta(s, a))Q(s, a) + \beta(s, a)\tilde{Q}(s, a)
$$

- $\bullet$   $\beta$  is a weighting parameter for state s and action a
	- It depends on the number of simulations that have been seen
		- When only a few simulations have been seen the AMAF value has to be weighted more highly  $(\beta(s, a) \approx 1)$ .
		- When many simulations have been seen, the MC value is weighted more highly(  $\beta(s, a) \approx 0$ )
- Heuristic MC-Rave: add a heuristic that initializes node values

#### **UCT-RAVE**



Application of the optimism-in-the-face-of-uncertainty principle

$$
Q_{\star}^{\oplus}(s, a) = Q_{\star}(s, a) + c \sqrt{\frac{\log N(s)}{N(s, a)}}
$$

# **Playing Go**



- For the last 30 years computers have evaluated Go positions by using handcrafted heuristics, based on human expert knowledge, patterns, and rules
- With MC no human knowledge about positions is required
- When heuristic MCTS was added to MoGo it was the first program to reach the dan (master) level and the first to beat a professional player
- Traditional programs rated about 1800 Elo
- MC programs with RAVE rated about 2500 Elo
- After initial jump of MC programs in go
	- Computer programs improved about one rank every year

# **Playing Bridge**



- GIB: Imperfect Information in a Computationally Challenging Game (Ginsberg, 2001)
- Used MC for generating deals that are consistent with both the bidding and the play of the deal thus far
- MC used for card play and bidding (though reliant on big bidding database)

# **Playing Scrabble**



- World-championship-caliber Scrabble (Sheppard, 2001)
- MAVEN on of the first programs to employ simulated games for the purpose of positional analysis
- Different algorithms for early-, mid-, and endgame
	- Problem the earlygame engine favors move A, but the midgame engine prefers another move B
	- Simulation can be used here to get an answer
	- Just simulate out the game after the moves A and B and calculate the winning probability for each move

# **Playing Scrabble**



- MAVEN averages 35.0 points per move, games ar over in 10.5 moves and MAVEN plays 1.9 bingos per game
- Human experts average 33.0 points, 11.5 moves per game and about 1.5 bingos per game
- MAVEN is stronger than any human



- On the Laziness of Monte-Carlo Game Tree Search in Non-tight situations (Althofer, 2008)
- Invented the double step race
	- Every move you are allowed to move either 1 or 2 squares
	- The player first to reach the green square wins



- For a human the optimal strategy is obvious: always move 2 squares except you are 1 square away from the finish
- The figure shows an example of a 6-vs-6 Double Step Race



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#### **Experiment**

- $\blacksquare$  Look at different DSRs (6-vs-3 6-vs-10), play 10.000 games.
- The game tree was generated by playing n random games from the starting position
- Table: Number of wins for Black (from 10.000 games)





Table: Number of games with a bad single step on the first move for Black



 Evaluation: MC performs better in tight positions, when Black already has an advantage, it tends to be "lazy"



- Game Self-Play with Pure Monte-Carlo: The Basin Structure (Althofer, 2010)
	- Continuation on the first paper
	- Self play experiments
		- One two MC players (with different MC parameters) play the Double Step Race
			- $M<sub>C</sub>(k)$  vs MC(2k) for example

















# **Evaluation**



- This "basin" structure also appeared in other games
	- E.g., Clobber, conHex, "Fox versus Hounds", "EinStein wurfelt nicht"
	- Some even had double basins
- "… it is not clear which applications the knowledge about the existence and shape of self-play basins will have."



- More simulations do not always lead to better results (Browne, 2010)
	- For example in a game of Gomoku flat MC fails to find the right move a
		- **Problem is move b creates two next-move wins for Black as** opposed to one next-move win for white even though it is White's turn next move
		- This improves however when using tree search
		- Though it takes a long time to converge





# **QUESTIONS**

# **References**



- Expected-Outcome: A General Model of Static Evaluation, Abramson, 1990
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