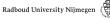
# Kernel Principal Component Ranking: Robust Ranking on Noisy Data

Evgeni Tsivtsivadze Botond Cseke Tom Heskes

Institute for Computing and Information Sciences, Radboud University Nijmegen,
Toernooiveld 1, 6525 ED Nijmegen, The Netherlands
firstname.lastname@science.ru.nl



#### Presentation Outline

- 1 Motivation
- 2 Ranking Setting
- 3 KPCRank Algorithm
- **4** Experiments

 Real world data is usually corrupted by noise (e.g. in bioinformatics, natural language processing, information retrieval, etc.)

- Real world data is usually corrupted by noise (e.g. in bioinformatics, natural language processing, information retrieval, etc.)
- Learning on noisy data is a challenge: ML methods frequently use low-rank approximation of the data matrix

- Real world data is usually corrupted by noise (e.g. in bioinformatics, natural language processing, information retrieval, etc.)
- Learning on noisy data is a challenge: ML methods frequently use low-rank approximation of the data matrix
- Any manifold learner or dimensionality reduction technique can be used for de-noising

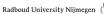
- Real world data is usually corrupted by noise (e.g. in bioinformatics, natural language processing, information retrieval, etc.)
- Learning on noisy data is a challenge: ML methods frequently use low-rank approximation of the data matrix
- Any manifold learner or dimensionality reduction technique can be used for de-noising
- Our algorithm is an extension of nonlinear principal component regression applicable to preference learning task

## Learning to Rank

#### Learning to rank (total order is given over all data points)

- Applications collaborative filtering in electronic commerce, protein ranking (e.g. RankProp: Protein Ranking by Network Propagation), parse ranking, etc.
- We aim to learn scoring function that is capable of ranking data points
- Several accepted settings for learning (ref. upcoming Preference Learning Book)
  - Object ranking
  - Label ranking
  - Instance ranking

 Main idea: Create new feature space with reduced dimensionality (only most expressive features are preserved) and use the ranking algorithm in that space to learn noise insensitive ranking function



- Main idea: Create new feature space with reduced dimensionality (only most expressive features are preserved) and use the ranking algorithm in that space to learn noise insensitive ranking function
- KPCRank scales linearly with the number of data points in the training set and is equal to that of KPCR

4 D > 4 P > 4 B > 4 B > B

- Main idea: Create new feature space with reduced dimensionality (only most expressive features are preserved) and use the ranking algorithm in that space to learn noise insensitive ranking function
- KPCRank scales linearly with the number of data points in the training set and is equal to that of KPCR
- KPCRank regularizes by projecting data onto lower dimensional space (number of principal components is a model parameter)

- Main idea: Create new feature space with reduced dimensionality (only most expressive features are preserved) and use the ranking algorithm in that space to learn noise insensitive ranking function
- KPCRank scales linearly with the number of data points in the training set and is equal to that of KPCR
- KPCRank regularizes by projecting data onto lower dimensional space (number of principal components is a model parameter)
- In conducted experiments KPCRank performs better than the baseline methods when learning to rank from data corrupted by noise

## Dimensionality Reduction

Consider covariance matrix

$$C = \frac{1}{m} \sum_{i=1}^{m} \Phi(z_i) \Phi(z_i)^t = \frac{1}{m} \Phi(Z) \Phi(Z)^t$$

To find the first principal component we solve

$$Cv = \lambda v$$

The key observation:  $v = \sum_{i=1}^{m} a_i \Phi(z_i)$ , therefore,

$$\frac{1}{m}$$
Ka =  $\lambda$ a

$$\langle v^I, \Phi(z) \rangle = \frac{1}{\sqrt{m\lambda_I}} \sum_{i=1}^m a_i^I \langle \Phi(z_i) \Phi(z) \rangle = \frac{1}{\sqrt{m\lambda_I}} \sum_{i=1}^m a_i^I k(z_i, z)$$



We start with the disagreement error:

$$d(f,T) = \frac{1}{2} \sum_{i,j=1}^{m} W_{ij} \left| \operatorname{sign}(s_i - s_j) - \operatorname{sign}(f(z_i) - f(z_j)) \right|.$$

The least squares ranking objective is

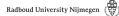
$$J(w) = (S - \Phi(Z)^t w)^t L(S - \Phi(Z)^t w)$$

and using projected data (reduced feature space) the objective can be rewritten as

$$J(\bar{w}) = (S - \Phi(Z)^t V \bar{w})^t L(S - \Phi(Z)^t V \bar{w})$$

Regularization is performed by selecting optimal number of principle components.





We set the derivative to zero and solve with respect to  $\bar{w}$ 

$$\bar{w} = \bar{\Lambda}^{\frac{1}{2}} (\bar{V}^t K L K \bar{V})^{-1} \bar{V}^t K L S$$

Finally we obtain the predicted score of the unseen instance-label pair based on the first p principal components by

$$f(z) = \sum_{l=1}^{p} \frac{1}{\sqrt{m\lambda_l}} \bar{w}_l \sum_{j=1}^{m} a_j^l k(z_j, z)$$

- · Efficient selection of the optimal number of principal components
- Detailed computation complexity considerations
- Alternative approaches for reducing computational complexity (e.g. subset method)



### **Experiments**

- Label ranking Parse Ranking dataset
- Pairwise preference learning Synthetic dataset based on sinc(x) function
- Baseline methods: Regularized least-squares, RankRLS, KPC regression, Probabilistic ranker.

## Parse Ranking Dataset

Method	Without noise	$\sigma = 0.5$	$\sigma = 1.0$
KPCR	0.40	0.46	0.47
KPCRank	0.37	0.41	0.42
RLS	0.34	0.43	0.46
RankRLS	0.35	0.45	0.47

Table: Comparison of the parse ranking performances of the KPCRank, KPCR, RLS, and RankRLS algorithms using a normalized version of the disagreement error as performance evaluation measure.

#### A Probabilistic Ranker

A probabilistic counterpart of the RankRLS algorithm would be regression with Gaussian noise and Gaussian processes prior. Given the score differences  $w_{ii} = s_i - s_i$ 

$$p(w_{ij}|f(x_i),f(x_i),v) = N(w_{ij}|f(x_i)-f(x_j),1/v).$$

Then the posterior distribution is

$$p(f|D,v,\theta) = \frac{1}{p(D|v,\theta)} \prod_{i,j=1}^{n} N(w_{ij}|f(x_i) - f(x_j), 1/v) N(f|0,K).$$

- The posterior distribution  $p(f|w,v,\theta)$  is Gaussian, its mean and covariance matrix can be computed by solving a system of linear equations and inverting a matrix, respectively.
- Note that predictions obtained by the RankRLS algorithm correspond to the predicted mean values of the Gaussian process regression Radboud University Nijmegen





#### Sinc Dataset

We use sinc function

$$sinc(x) = \frac{sin(\pi x)}{\pi x},$$

to generate the values used for creating magnitudes of pairwise preferences.

- We get 2000 equidistant points from the interval [-4, 4]
- Sample 1000 for constructing the training pairs and 338 for constructing the test pairs
- From these pairs we randomly sample 379 used for the training and 48 for the testing

The magnitude of pairwise preference is calculated as

$$w = sinc(x) - sinc(x').$$





#### Sinc Dataset

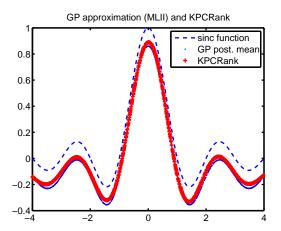


Figure: The sinc function and the approximate posterior means of the f using the preference with magnitudes and KPCRank predictions



Thank you.

